

Background

Computational Methods for Fluid Flow

Need to efficiently compute steady flow states to enable

- Implicit time stepping strategies
- Improved stability analysis
- Classification of flow bifurcations

Fluid Models

Incompressible Navier Stokes

$$\frac{\partial \vec{u}}{\partial t} - \nu \nabla^2 \vec{u} + (\vec{u} \cdot \nabla) \vec{u} + \nabla p = \vec{f} \quad \text{in } \Omega,$$

$$\nabla \cdot \vec{u} = 0 \quad \text{in } \Omega.$$

Advection-Diffusion

$$-\nabla^2 u + (\vec{w} \cdot \nabla) u = g$$

Viscous and Inertial forces occur on disparate scales lead to sharp flow features which:

- require fine numerical grid resolution
- cause **poorly conditioned** non-symmetric system.

Spatial Discretization

Spectral Element Method

On each element, the solution is expressed via a nodal basis

$$u_e^N(x, y) = \sum_{i=1}^{N+1} \sum_{j=1}^{N+1} u_{ij} \pi_i(x) \pi_j(y). \quad (1)$$

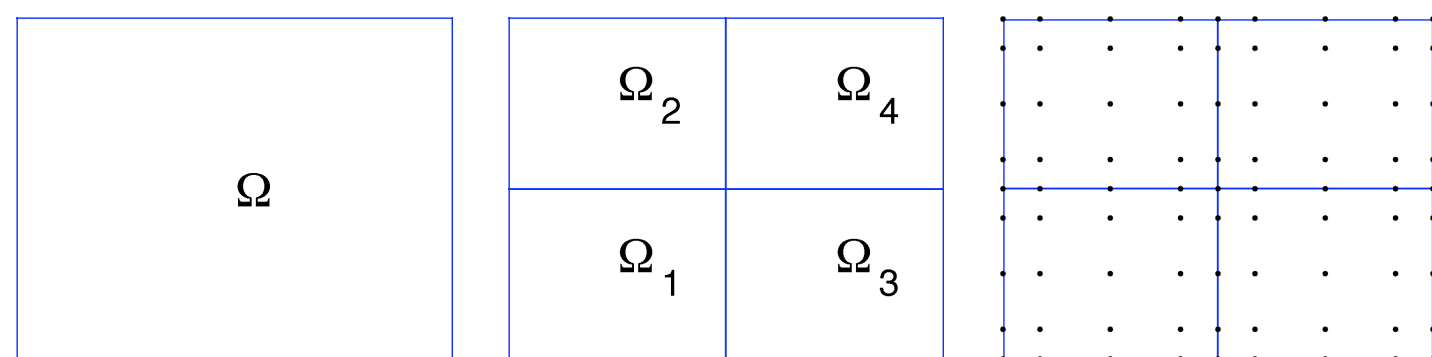


Figure: Simulation domain Ω (left) is divided into elements (middle). In each element grid points based on Gauss-Legendre-Lobatto nodes are chosen (right).

Spectral Basis Functions

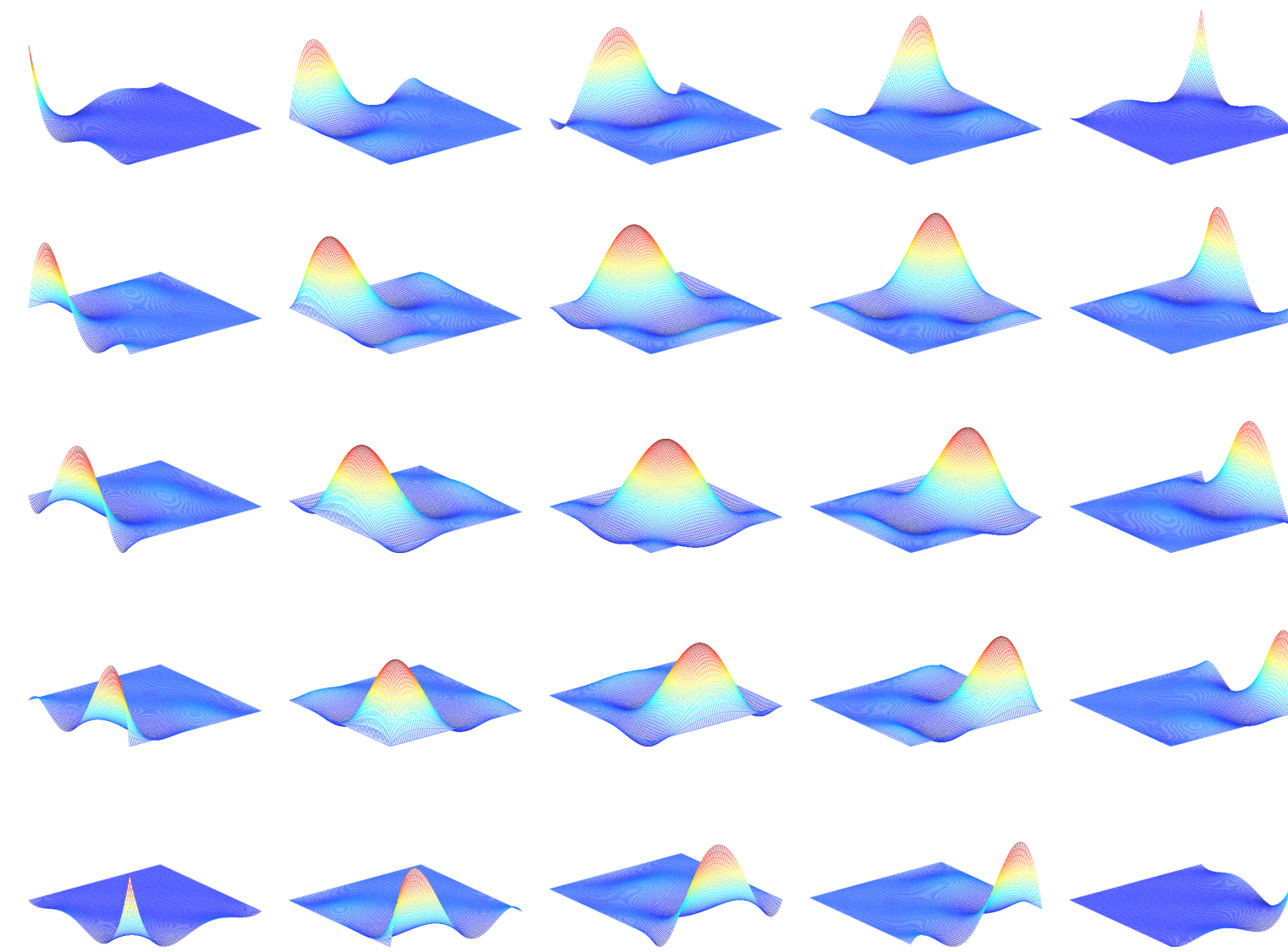


Figure: 4th Order 2D Lagrangian nodal basis functions $\pi_i \otimes \pi_j$ based on the Gauss-Labotto-Legendre points.

Fluid Simulation Layout

Time step (BE) $x^{n+1} = x^n + \Delta t F(t^{n+1}, x^{n+1})$

Nonlinear Solver (Newton) $x_{k+1} = x_k + \Delta x_k$

Linear Solver (GMRES) $A \Delta x_k = b$

Preconditioner (DD) $AP^{-1}P \Delta x_k = b$

Domain Decomposition System

$$\begin{bmatrix} \bar{P}_{II}^1 & 0 & \dots & 0 & \bar{P}_{I\Gamma}^1 \\ 0 & \bar{P}_{II}^2 & 0 & \dots & \bar{P}_{I\Gamma}^2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & \bar{P}_{II}^E & \bar{P}_{I\Gamma}^E \\ 0 & 0 & \dots & 0 & \bar{P}_S \end{bmatrix} \begin{pmatrix} u_{I1} \\ u_{I2} \\ \vdots \\ u_{IE} \\ u_\Gamma \end{pmatrix} = \begin{pmatrix} \hat{b}_{I1} \\ \hat{b}_{I2} \\ \vdots \\ \hat{b}_{IE} \\ g_\Gamma \end{pmatrix}$$

$\bar{P}_S = \sum_{e=1}^E (\bar{P}_{\Gamma\Gamma}^e - \bar{P}_{\Gamma I}^e \bar{P}_{II}^{e-1} \bar{P}_{I\Gamma}^e)$ represents the Schur complement of the system. The interface u_Γ is obtained via an iterative solve.

Constant Wind Approximation

When the “wind” \vec{w} is **constant on each element**, then element interiors can be obtained via **Fast Diagonalization** and $P^{-1} = A^{-1}$.

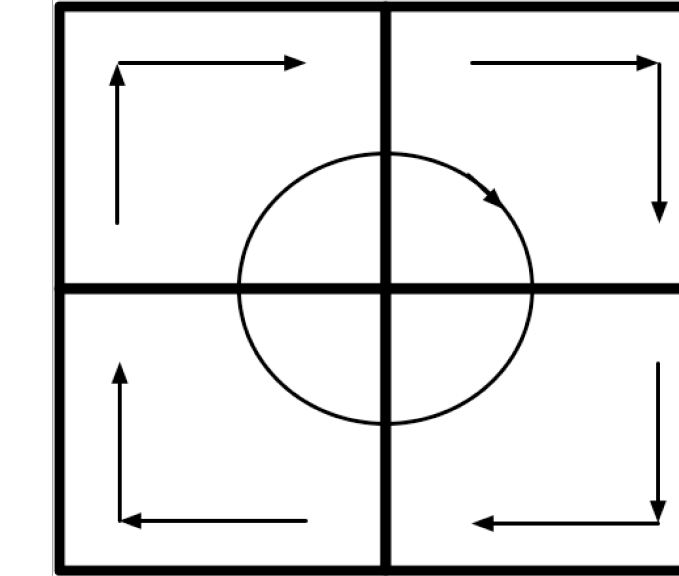


Figure: Illustration of a constant wind approximation

Otherwise using a constant wind approximation on each element $P^{-1} \approx A^{-1}$.

$$\bar{P}^{e-1} = \tilde{M}(V_y \otimes V_x)(\Lambda_y \otimes I + I \otimes \Lambda_x)^{-1}(V_y^{-1} \otimes V_x^{-1})\tilde{M}$$

Test Case: Constant Wind, Pc=400

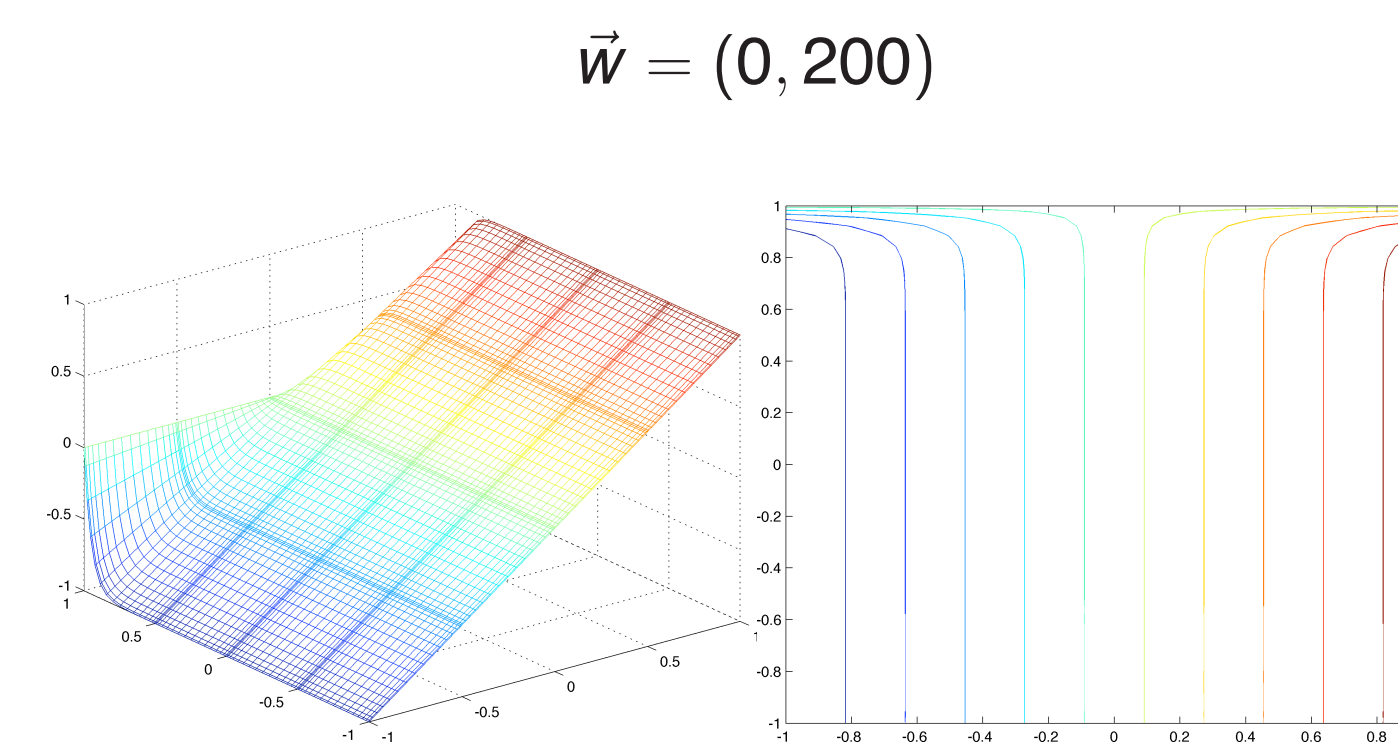


Figure: Steady flow with constant wind exhibiting boundary layer at $y = 1$ using SEM $N=16$ & $E=4 \times 4$.

Interface Solver Convergence

Table: Iteration count ($E=4 \times 4$)

N	Iterations -	Iterations R-R
4	240	44
8	108	42
16	103	43

Table: Iteration count ($N=4$)

E	Iterations -	Iterations R-R
4×4	240	44
8×8	175	42
16×16	143	50

Robin-Robin preconditioned interface solve (R-R) is **invariant** to the number of points in the discretization and converges in **significantly fewer steps** than the non-preconditioned system (-).

Test Case: Recirculating Wind, Pc=400

$$\vec{w} = 200(y(1 - x^2), -x(1 - y^2))$$

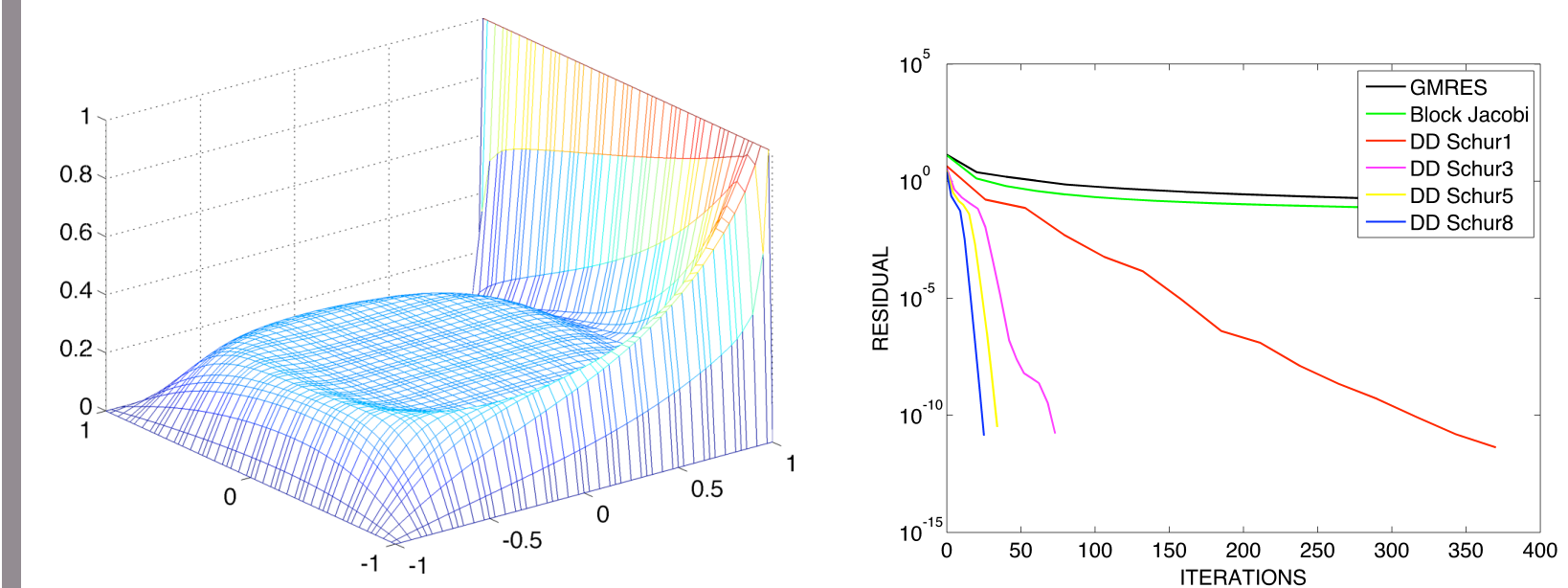


Figure: Computed solution of steady flow with recirculating wind using SEM $N=4$ & $E=12 \times 12$.

Figure: Comparison of Outer iterations when inner iterations are varied.

Convergence Properties for Refined Meshes

Table: Iteration Count ($E=4 \times 4$)

N	Number of Outer Iterations
5	52
7	56
9	55
11	53
13	51

Table: Iteration count ($N=4$)

E	Number of Outer Iterations
10×10	37
11×11	38
12×12	38
13×13	38

Summary & Future Directions

Summary

- Improved simulation efficiency for steady Advection-Diffusion equation

Future Directions

- Improve wind approximation on each element
- Coarse Grid Preconditioner to allow for more elements
- Use Preconditioner in Navier-Stokes simulations
- Apply to realistic fluid simulations

References

- P. A. Lott, “Fast Solvers for Models of Fluid Flow”, Ph.D. Thesis University of Maryland College Park, 2008
- P. A. Lott and H. Elman, “Matrix-free preconditioner for the steady advection-diffusion equation with spectral element discretization”, in preparation, 2008
- _____, “Matrix-free Block preconditioner for the Navier-Stokes equations”, in preparation, 2008